Mutual attraction

Hopefully, you found it helpful that we started with a simple scenario one object attracts another object—and moved on to one object attracts many objects. However, it's likely that you are going to find yourself in a slightly more complex situation: many objects attract each other. In other words, every object in a given system attracts every other object in that system (except for itself).

We've really done almost all of the work for this already. Let's consider a program with an array of Mover objects:

```
var movers = [];
for (var i = 0; i < movers.length; i++) {
    movers[i] = new Mover(random(0.1, 2), random(width), random(height));
}
draw = function() {
    background(255, 255, 255);
    for (var i = 0; i < movers.length; i++) {
        movers[i].update();
        movers[i].display();
    }
};
```

The draw() function is where we need to work some magic. Currently, we're saying: "for every mover i, update and display yourself." Now what we need to say is: "for every mover i, be attracted to every other mover j, and update and display yourself."

for (var i = 0; i < movers.length; i++) {</pre>

```
// For every Mover, check every Mover!
for (var j = 0; j < movers.length; j++) {
    var force = movers[j].calculateAttraction(movers[i]);
    movers[i].applyForce(force);
}
movers[i].update();
movers[i].display();</pre>
```

}

In the previous example, we had an Attractor object with a method named calculateAttraction(). Now, since we have movers attracting movers, all we need to do is copy that method into the Mover object.

```
Mover.prototype.calculateAttraction = function(m) {
  var force = PVector.sub(this.position, m.position);
  var distance = force.mag();
  distance = constrain(distance, 5.0, 25.0);
  force.normalize();
  var strength = (G * this.mass * m.mass) / (distance * distance);
  force.mult(strength);
  return force;
};
```

Of course, there's one small problem. When we are looking at every mover i and every mover j, are we OK with the times that i equals j? For example, should mover #3 attract mover #3? The answer, of course, is no. If there are five objects, we only want mover #3 to attract 0, 1, 2, and 4, skipping itself. We do, however, want to calculate and apply both the force from mover #3 on mover #1, and mover #1 on mover #3. The calculated forces will be the same for the pair, but the resulting acceleration will be different, depending on the mass of each mover. Our attraction table should look like:

 $\begin{array}{c} 0 & \longrightarrow & 1, \, 2, \, 3, \, 4 \\ 1 & \longrightarrow & 0, \, 2, \, 3, \, 4 \\ 2 & \longrightarrow & 0, \, 1, \, 3, \, 4 \\ 3 & \longrightarrow & 0, \, 1, \, 2, \, 4 \end{array}$

And so, we finish this example by modifying our for loop so that the inner loop avoids movers attracting themselves:

```
for (var i = 0; i < movers.length; i++) {
    for (var j = 0; j < movers.length; j++) {
        if (i !== j) {
            var force = movers[j].calculateAttraction(movers[i]);
            movers[i].applyForce(force);
        }
    }
    movers[i].update();
    movers[i].display();
}</pre>
```

Let's see it all together now:

var G = 1;

```
var Mover = function(m, x, y) {
  this.mass = m;
  this.position = new PVector(x, y);
  this.velocity = new PVector(0, 0);
  this.acceleration = new PVector(0, 0);
```

```
Mover.prototype.applyForce = function(force) {
    var f = PVector.div(force, this.mass);
    this.acceleration.add(f);
```

```
};
```

```
Mover.prototype.update = function() {
  this.velocity.add(this.acceleration);
  this.position.add(this.velocity);
  this.acceleration.mult(0);
```

```
};
```

```
Mover.prototype.display = function() {
```

stroke(0);

strokeWeight(2);

```
fill(255, 255, 255, 127);
```

ellipse(this.position.x, this.position.y, this.mass*16, this.mass*16);

```
};
```

```
Mover.prototype.calculateAttraction = function(m, i) {
```

// Calculate direction of force

```
var force = PVector.sub(this.position, m.position);
```

```
// Distance between objects
```

```
var distance = force.mag();
```

// Limiting the distance to eliminate "extreme" results for very close or very far objects

distance = constrain(distance, 5.0, 25.0);

// Normalize vector (distance doesn't matter here, we just want this vector for direction

force.normalize();

```
// Calculate gravitional force magnitude
```

var strength = (G * this.mass * m.mass) / (distance * distance);

```
// Get force vector --> magnitude * direction
```

force.mult(strength);

return force;

```
};
```

var movers = [];

```
for (var i = 0; i < 5; i++) {
```

movers[i] = new Mover(random(0.1, 5), random(width), random(height));

```
}
```

};

```
var draw = function() {
```

```
background(50, 50, 50);
```

```
for (var i = 0; i < movers.length; i++) {
  for (var j = 0; j < movers.length; j++) {
     if (i !== j) {
        var force = movers[j].calculateAttraction(movers[i]);
        movers[i].applyForce(force);
     }
     movers[i].update();
     movers[i].display();
}</pre>
```